

Description of molecules represented by their 3D structures. Descide whether the molecules will form a complex (interact/bind). Determine the binding affinity. Deduce function.



Biological Motivation Proteins act by interaction – assembly and disassembly of multimolecular complexes. Drug development: Disruption of multi-molecular interactions. Design of protein-drug complexes. Structural Elucidation of the Large Molecular Machines of the Cell – Ribosome, Proteasome etc.

H.J. Wolfson -- INRIA



Forces governing biomolecular recognition

Depend on the molecules involved and the solvent.

- Van der Waals.
- · Electrostatics.
- Hydrophobic contacts.
- Hydrogen bonds
- Salt bridges .. etc.

All interactions act at short ranges.

Implies that a necessary condition for tight binding is molecular surface complementarity.

H.J. Wolfson -- INRIA

Dec 2014

Geometric Docking Algorithms

- Based on the assumption of shape complementarity between the participating molecules.
- Molecular surface complementarity proteinprotein, protein-ligand, (protein - drug).
- Hydrogen donor/acceptor complementarity protein-drug.
- <u>Remark</u>: usually "protein" here can be replaced by "DNA" or "RNA" as well.

H.J. Wolfson -- INRIA

Dec 2014

Issues to be examined when evaluating docking methods

- Rigid docking vs Flexible docking :
- If the method allows flexibility:
 - Is flexibility allowed for ligand only, receptor only or both ?
 No. of flexible bonds allowed and the cost of adding additional flexibility.
- Does the method require prior knowledge of the active site ?
- Performance in "unbound" docking experiments.
- Speed ability to explore large libraries.

H.J. Wolfson -- INRIA



Unbound Docking

- In the unbound docking we are given 2 molecules in their native conformation.
- · The goal is to find the correct association.
- Problems: conformational changes (side-chain and backbone movements), experimental errors in the structures.

H.J. Wolfson -- INRIA









Detect a <u>3D rigid transformation</u> of one of the molecules that docks it to the other maximal interface and negligent shape penetration.

H.J. Wolfson -- INRIA











Connolly's MS algorithm - cont.

- Convex, concave and saddle patches according to the no. of contact points between the surface atoms and the probe ball.
- Outputs points+normals according to the required sampling density (e.g. 10 pts/A²).

H.J. Wolfson -- INRIA

Dec 2014

Critical points based on Connolly rep. (Lin, Wolfson, Nussinov, Proteins 1994)

- Define a single point+normal for each patch.
- Convex-caps, concave-pits, saddle belt.

H.J. Wolfson -- INRIA

Active Site Focusing (optional)

There are major differences in the interactions of different types of molecules (protease-inhibitor, antibody-antigen, protein drug). Studies have shown the presence of energetic *hot spots* in the active sites of the molecules.

Protease/inhibitor – select patches with high enrichment of hot spot residues (Ser,Gly,Asp and His for protease; and Arg,Lys,Leu,Cys and Pro for protease inhibitor).

Antibody/antigen – 1.detect CDRs of the antibody. 2. select hot spot patches (Tyr,Asp,Asn,Glu,Ser and Trp for antibody; and Arg,Lys,Asn and Asp for antigen)

Protein/drug – select largest protein cavity (highest value of average shape function for the patch)

Local Feature Extraction

- Connolly points + normals dense.
- Lin et al. points sparser.
- Knobs holes (Connolly; Norel-Nusinov-Wolfson) – sparse crude curvature evaluation.

H.J. Wolfson -- INRIA





Patch Detection by Segmentation

- Construct a sub-graph for each type of points: knobs, holes, flats. For example G_{knob} will include all surface points that are knobs and an edge exists between two 'knobs' if they belong to the same atom.
- Compute connected components of every subgraph.
- Problem: the sizes of the connected components can vary.
- Solution: apply 'split' and 'merge' routines.

H.J. Wolfson -- INRIA

Dec 2014

<section-header><complex-block>





H.J. Wolfson - INRIA





Hash Table Key is Invariant to the Rigid (Euclidean) Transformation

- Euclidean and geodesic distances between the points: dE, dG
- The angles *a*, β between the [a,b] segment and the normals
- The torsion angle $\boldsymbol{\omega}$ between the planes



Pose Clustering, Clash Detection & Scoring Stage

- Since local features are matched, we usually have multiple instances of "almost" the same transformation.
- Some transformations may induce steric clashes.
- Pose clustering, steric clash filtering and scoring are applied to the transformation list.

H.J. Wolfson -- INRIA











Predictor group	TOS	TOP	T10	T11	T12	T13	T34	T18	T19	Predictor summar
All a strate		0			-					diametowne
This Manager	-				-		-	-	-	alure in
Wend		8	2	· ·	<u> </u>	<u></u>		<u> </u>	<u></u>	1000
Bates		ŏ				0				1000
Bahor		ŏ	0					0		6/0mm/4mm
Camacho		ŏ	õ					-		A11000/10000
Grav		_	_			0	0			\$23mm(),mmm
Bussia		_			0	-		- ñ		52100/2000
CharDen		0						- iii		\$10mm/3 mmm
Stendere		õ	ő			0		- ŭ		5/2**
Einenstein		ŏ	ő			ő		- ă		4/1==/2===
Ditchie		ň	ň					- iii	ě.	4/100/1000
Zhou	-	_	õ		***		-		ŏ	4/1-1/1
Ten Elock	0	0	0						ö	3/1=2/2===
Zecharias	÷.	ö	_	_	_			0		3/2**/1***
Valencia		ö	0				0	0		3
Valuer		_	0					-	0	2/2***
Unevana	0	0	0	-		0	0	0	0	2/1***
Kennessis			0			0	0		0	5/1
Fano			0		0	0	0	0	0	1
Gottschalk										1
Palma	0	0	0		0	0	0	0	0	1
Poupon					0		0	0	0	1
Wong	0	0	0		0	0	0	0	0	1
Torot support	11/7**/2***	1	4/1***	15/7**	16/11****	10/2**/4***	1477-025-0	340**	10(4**/1***	
This table summa- target. Column 1 hats the summarizes the re V indicates that a least one of the sy scenracy, and *** range used to real to	rines the results name of the pri- seults per predi- one of the sub- builted predict 'indicates that the prediction	i obtais dur gr itted p tione v at leas s.	investig org, and rediction rat in th t-one pr	I the gros ator. The "the botto serves of a screpts edictics w vertable p	pa thataulo nant 9 colum n row auno acceptable q hie range. ' rae of high o redictions. (nitted on even and last the resu- nations the resu- sality. '' indi- states the coursecy. See the followed by the	ore predictions the obtained for the par target, outes that no p at at least one o text as well number of pre-	reach o reach o rediction of the s ar Bef. 1 Listions	Aable quality o Ithe 9 targets: a ware submitt ubmitted pred 1 for the defini- of medium and	rbetter for at least on The right-most column of. * indicates that a intione was of medium tion of the parameter high accuracy denotes







Dec 2014

GRP94 molecule

There was no structure of grp94 protein. Homology modeling was used to predict a structure using another protein with 52% identity.



Recently the structure of grp94 was published. The RMSD between the crystal structure and the model is 1 30. HJ. Wolfson-INRIA Dec 2014 is 1.3A.

GRP94 molecule

- There is a binding site for inhibitors between the helices.
- There is another cavity produced by a β -sheet on the opposite side.



Docking

- · PatchDock was applied to dock the two molecules, without any binding site constraints.
- Interestingly, the better scoring docking results were clustered in the two cavities:













Some PatchDock Publications

- D. Duhovny, R. Nussinov, H.J. Wolfson, *Efficient* Unbound Docking of Rigid Molecules, 2'nd Workshop on Algorithms in Bioinformatics (WABI'02), Sept. 2002, Lecture Notes in Computer Science 2452, pp. 185-200, Springer Verlag.
- D. Schneidman-Duhovny, et al., Taking Geometry to its Edge: Fast Unbound Rigid (and Hinge-bent) Docking, Proteins, 52, 107—112, (2003).
- D. Schneidman-Duhovny, Y. Inbar, R. Nussinov and H. J. Wolfson, PatchDock and SymmDock: servers for rigid and symmetric docking, Nuc. Acids Res., 33 (NAR, web server issue), W363—W367, (2005).

Dec 2014 H.J. Wolfson -- INRIA